

80 Pages
27.6 cm x 21.2 cm

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EXERCISE BOOK CAHIER D'EXERCICES

NAME/NOM _____

SUBJECT/SUJET CPSC 259



ASSEMBLED IN CANADA WITH IMPORTED MATERIALS
ASSEMBLÉ AU CANADA AVEC DES MATIÈRES IMPORTÉES

12107

Arrays

```
int age[100];
```

```
const int Days = 365;
```

```
double temperatures[Days];
```

```
int Days = 365;
```

```
double temperatures[Days];
```

NO!

0	1	2	3	4	5	6	7	8	9	10
---	---	---	---	---	---	---	---	---	---	----

- Arrays can be initialized (filled) by using a loop

```
int marks[10];
```

```
for (int i = 0; i < 10; i++)
```

```
marks[i] = -1;
```

- or directly

```
int fib[] = {0, 1, 2, 3, 5, 8, 13};
```

```
arr1 = {1, 2, 3, 10};
```

NOT ALLOWED!

Ex. 2

Sum	index
0	1
4	2
12	3
28	4

Pointers

```
int a = 5;  
int *p = &a;
```

- a is an integer variable with value 5
- p is a pointer variable storing the address of a

Generic Pointer

```
void* gp;
```

Opening / Reading / Writing Files

• fgets function

```
char* fgets(char* str, int n, FILE* stream)
```

- reads a line from the file and stores it in string
- stops at (n-1), \n, or end of file

• sscanf function

```
int sscanf(const char* str, const char* format, ...)
```

Dynamic Memory

malloc function

$\text{ptr} = (\text{cast-type}^*) \text{malloc}(\text{byte-size});$

-returns a pointer to a memory block of at least size bytes

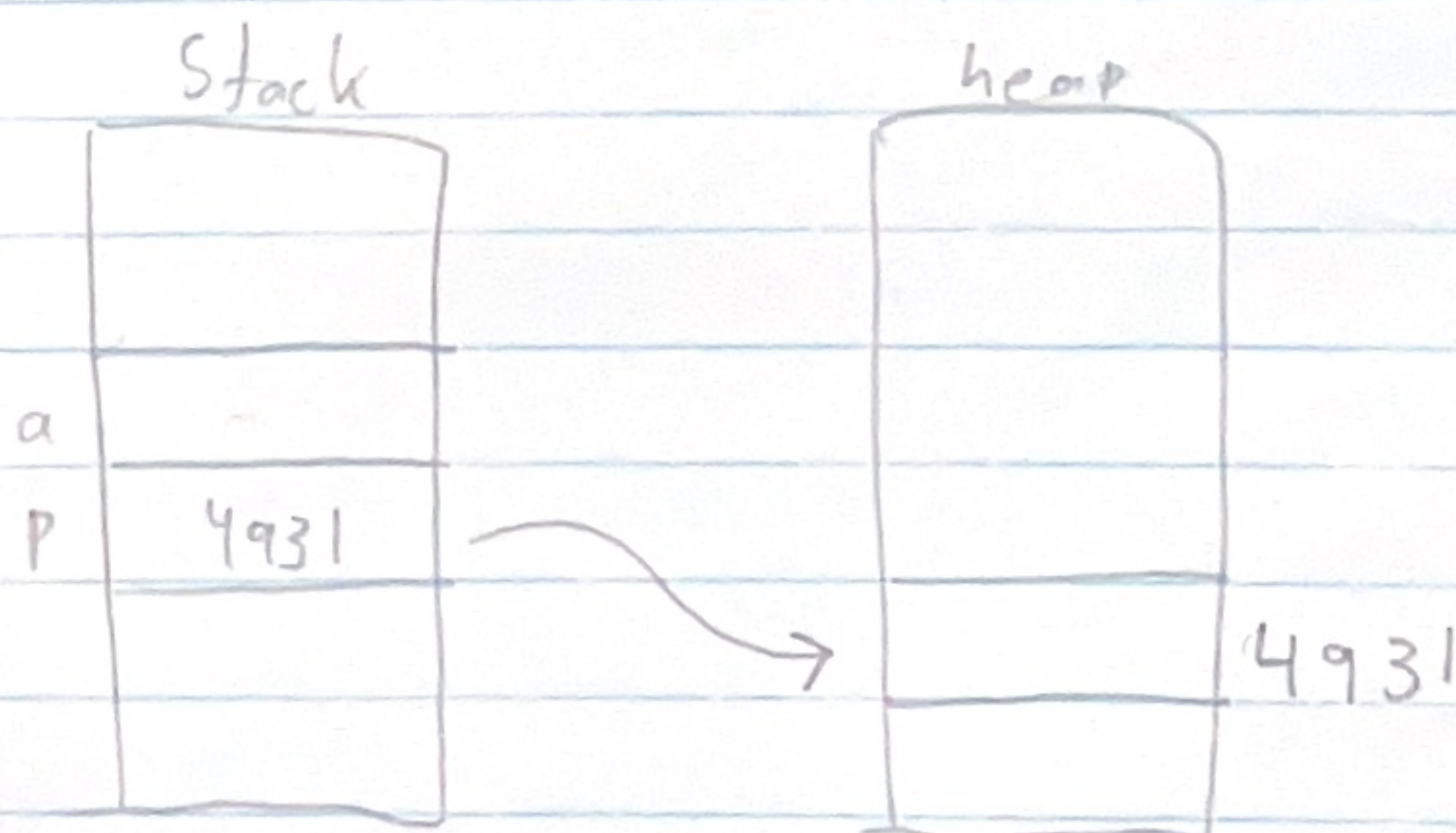
free function

$\text{free}(\text{ptr});$

-returns the previously allocated memory block

18

```
int main()  
{  
    int a;  
    int* p = (int*) malloc(sizeof(int));  
    *p = 10;  
}
```



Efficiency

9/24/18

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Code Runtime

- loop value n
- hardware
- compiler
- programming language

Running Time

- function of n
- $T(n)$
- Doesn't depend on hardware, mathematical analysis

Order Notation

Let $T(n)$ and $f(n)$ be functions mapping $\mathbb{Z}^+ \rightarrow \mathbb{R}^+$ (Positive ints)

$T(n) \in O(f(n))$ if there are constants c and n_0 such that $T(n) \leq c \cdot f(n)$ for all $n \geq n_0$

Meaning

$T(n)$ is in big O of $f(n)$

$T(n)$ will at least be better than $f(n)$ which is a function we understand

$$T(n) \in \Omega(f(n))$$

$$T(n) \geq C \cdot f(n)$$

$$T(n) \in O(f(n))$$

$$T(n) \leq C \cdot f(n)$$

"Growth no better than"
 $f(n)$

"No worse than $f(n)$ "

$T(n) \in \Theta(f(n))$ if $T(n) \in O(f(n))$ and $T(n) \in \Omega(f(n))$

" $T(n)$ grows at the same"
rate as $f(n)$

Eliminate low order terms

Linked Lists

10/04/18

Unordered Arrays

inserting an item $\rightarrow O(1)$

Taking an element out $\rightarrow$ Options:

① shift everything down 1

pro: order preserved

con: costly if lots after

② Take the last one and put it there

pro: cheap con: order not preserved

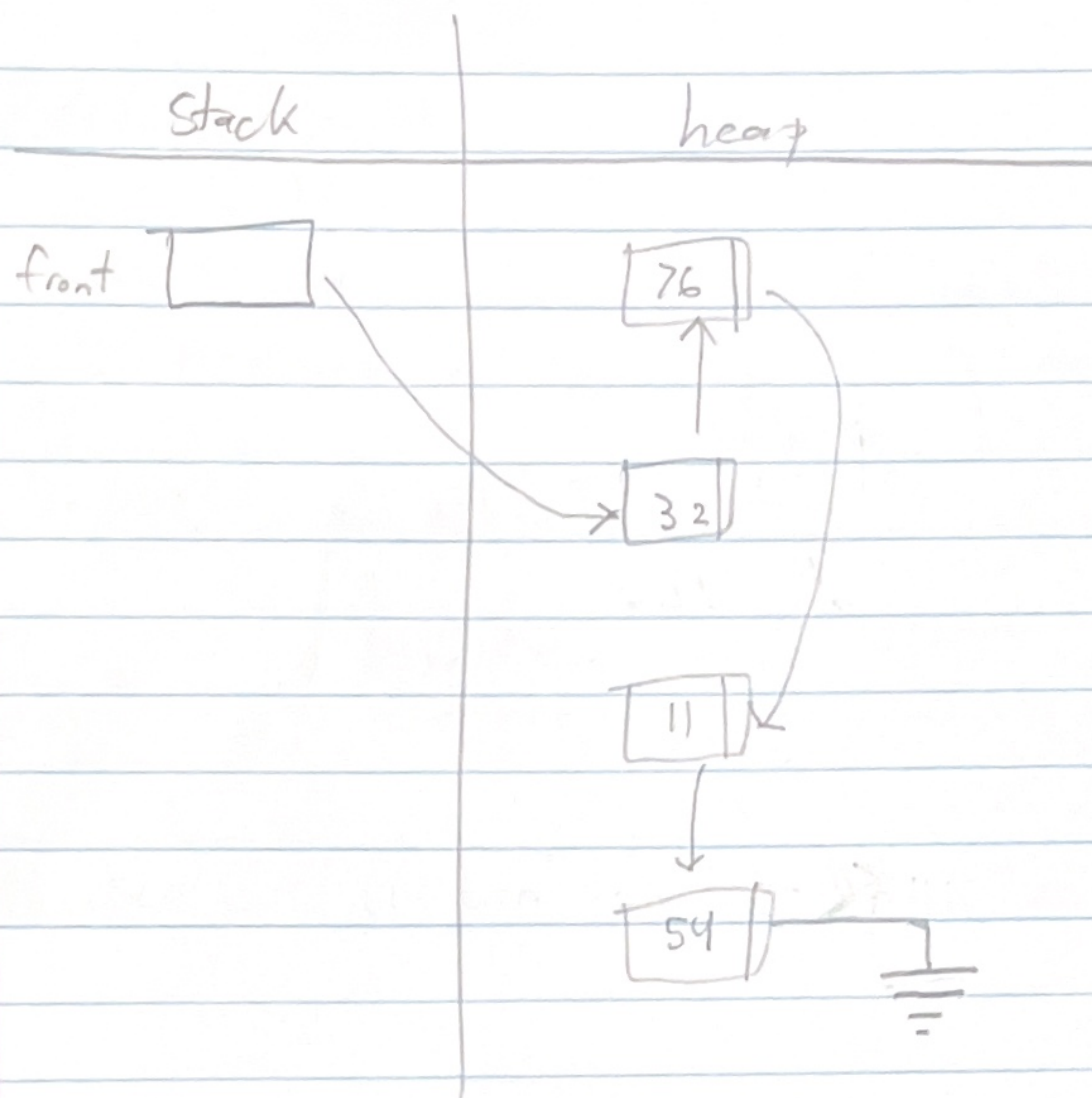
Ordered Arrays

inserting an item $\rightarrow O(n)$

Linked List

- made up of linked nodes
- In the heap

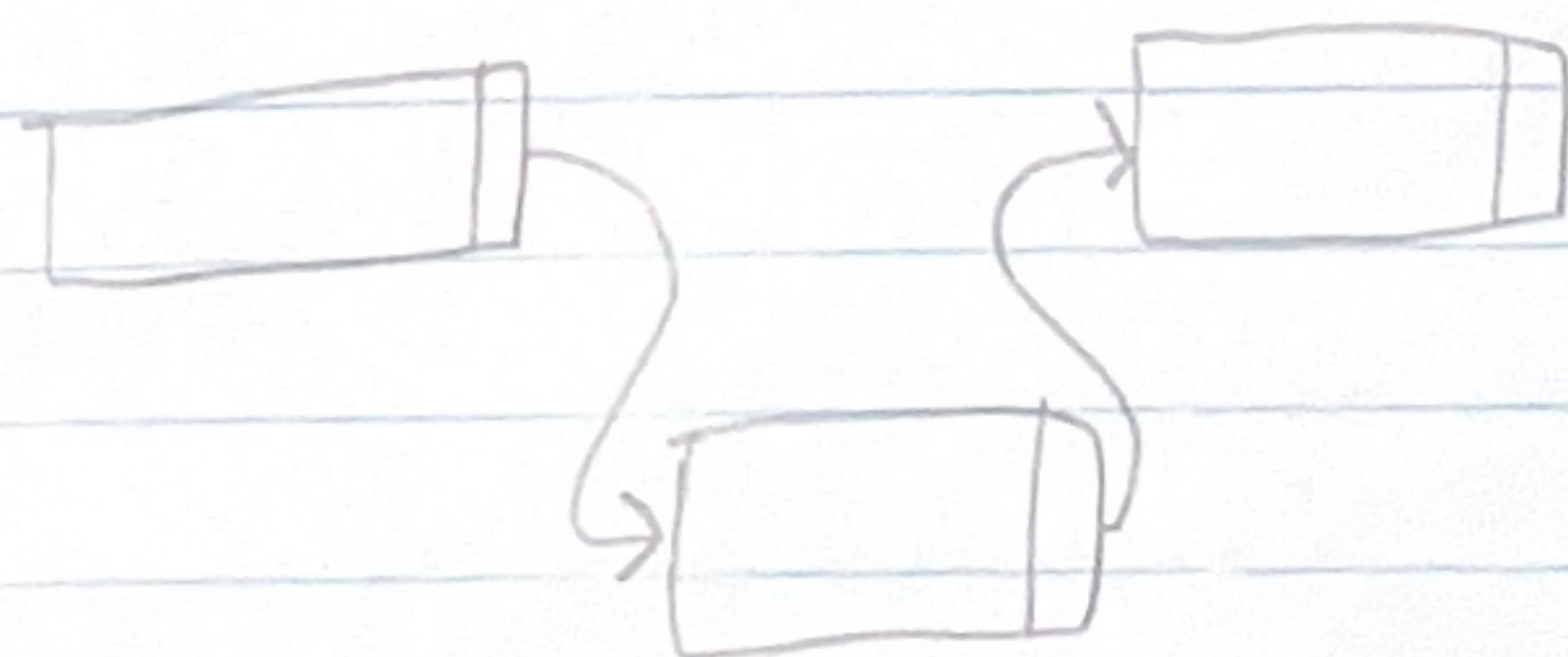
```
typedef struct node {  
    int data;  
    struct node * next;  
} node;
```

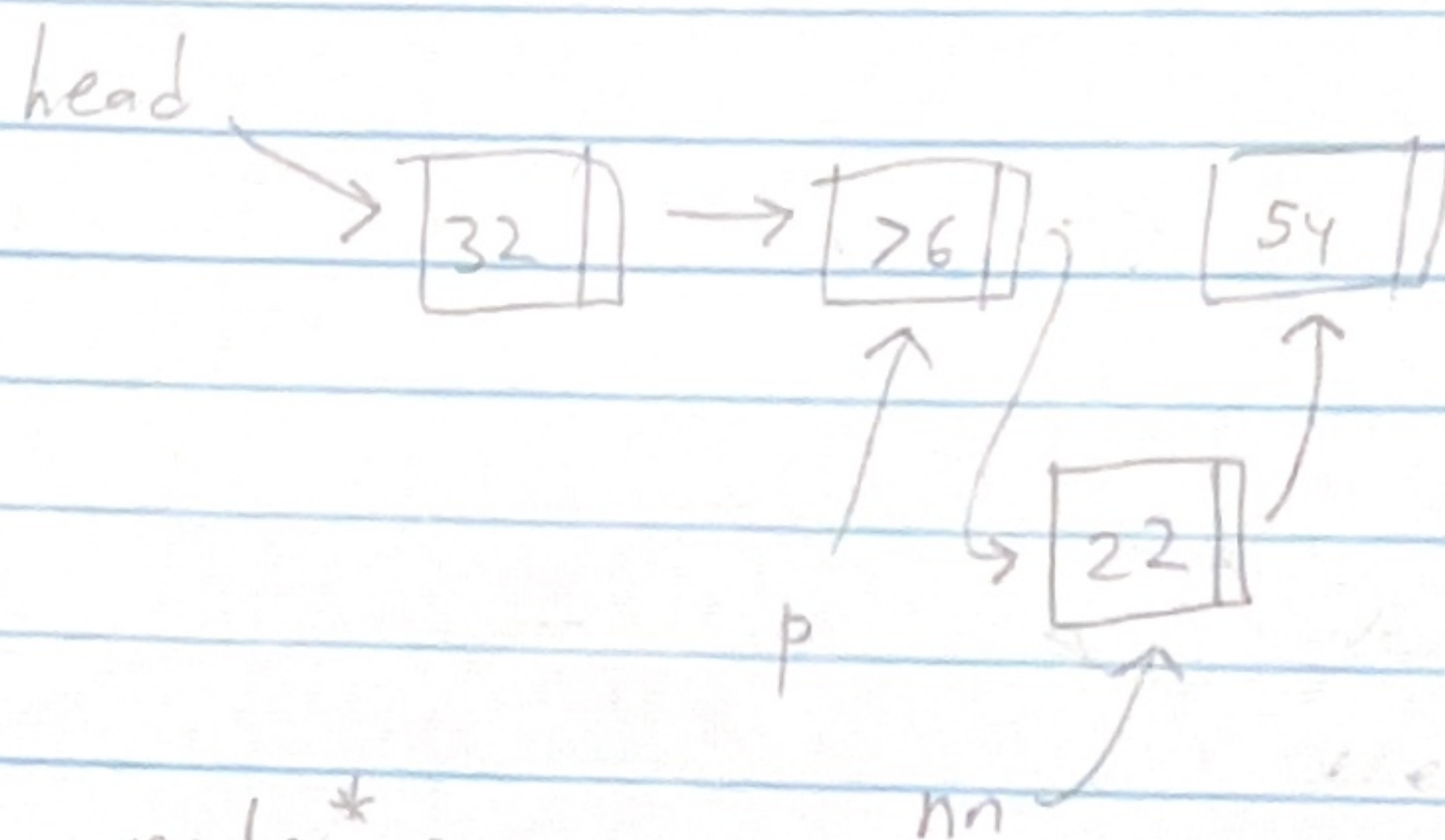


How do you know you're at the end?

last node has a pointer set to NULL

Inserting into a linked list





```

typedef struct node {
    int data;
    struct node *next;
} node;
  
```

* want to insert item

```

node * p;
p = head->next;
  
```

```

node * nn = (node *) malloc(sizeof(node));
  
```

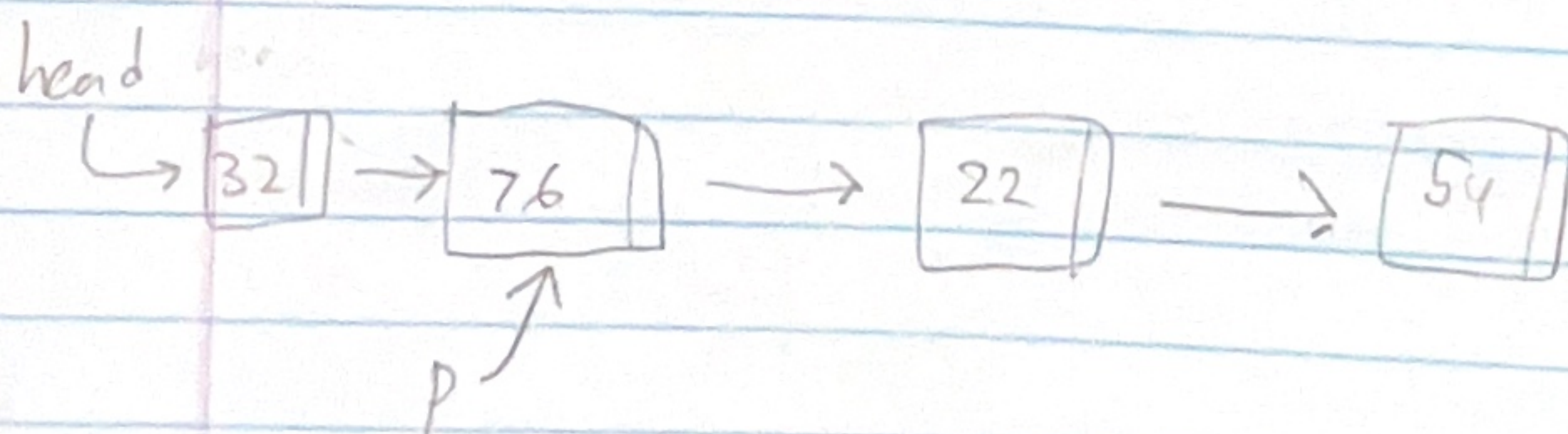
```

nn->data = 22;
// *nn.data = 22; is equivalent
  
```

```

nn->next = p->next;
p->next = nn;
  
```

Removing an item



```

node * rem = p->next;
  
```

```

p->next = p->next->next;
// (*(*p.next)).next is equivalent
  
```

```

free(rem);
  
```

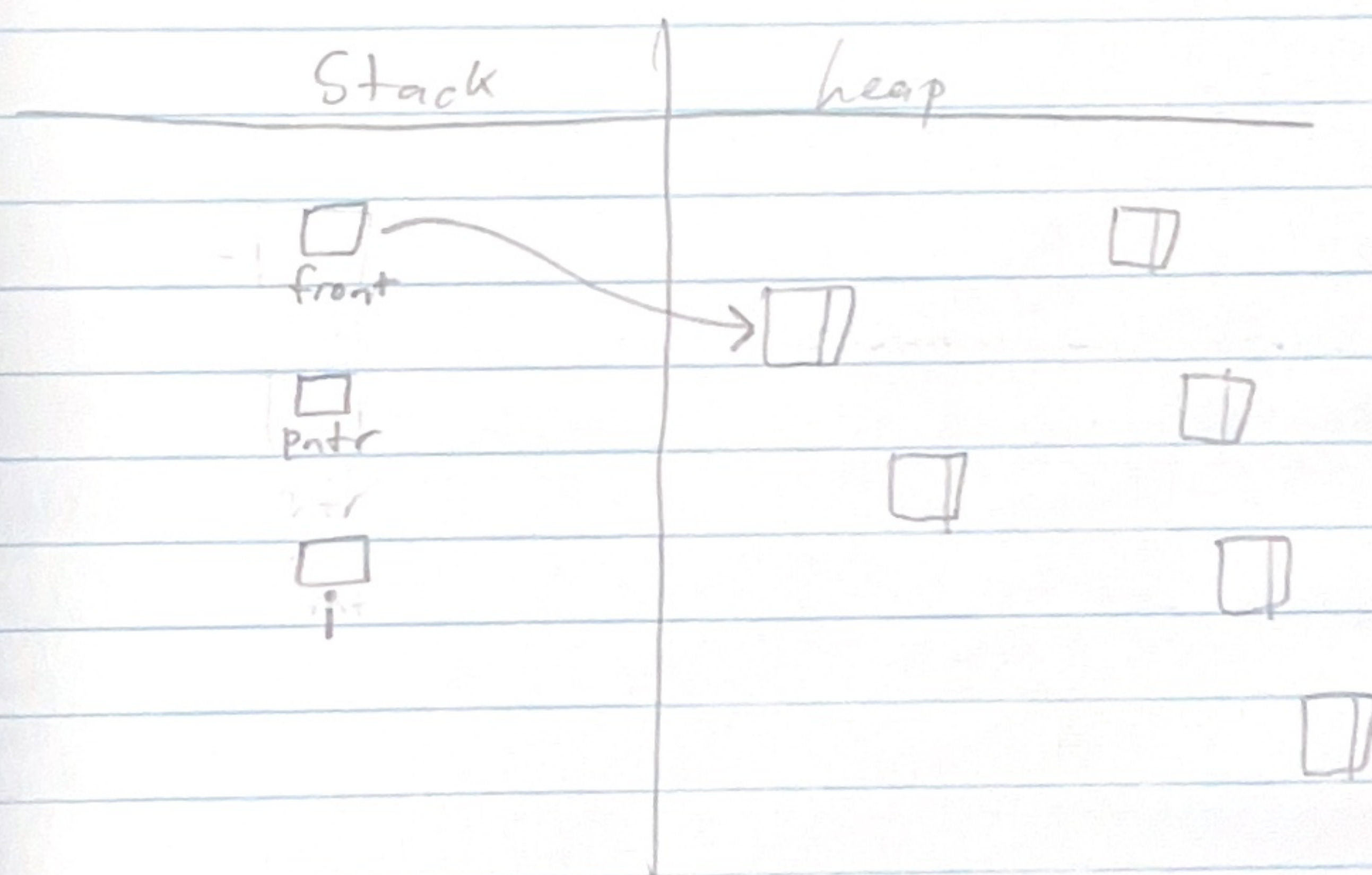
```
node* p = head;
```

```
while (.....) {  
    p = p -> next;  
}
```

————— To traverse the linked
list to get to a specific
node

Linked List

Linked List traversal



```
node* ptr = front;
```

```
int i;
```

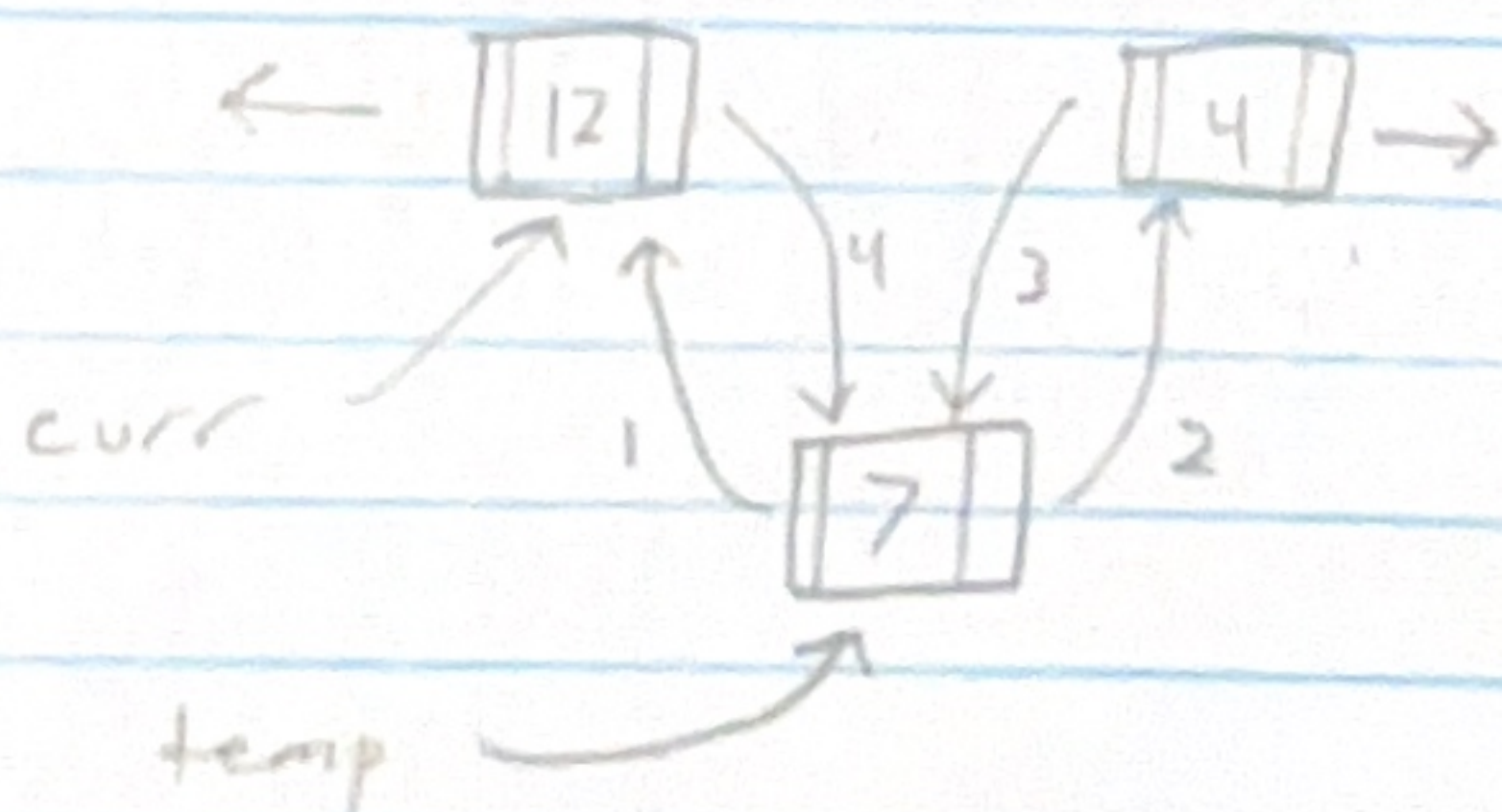
```
for (i = 0; i < 4; i++) {
```

```
    ptr = ptr -> next;
```

```
}
```

Doubly-linked List

```
typedef struct Node {  
    int data;  
    struct Node* prev;  
    struct Node* next;  
} Node;
```



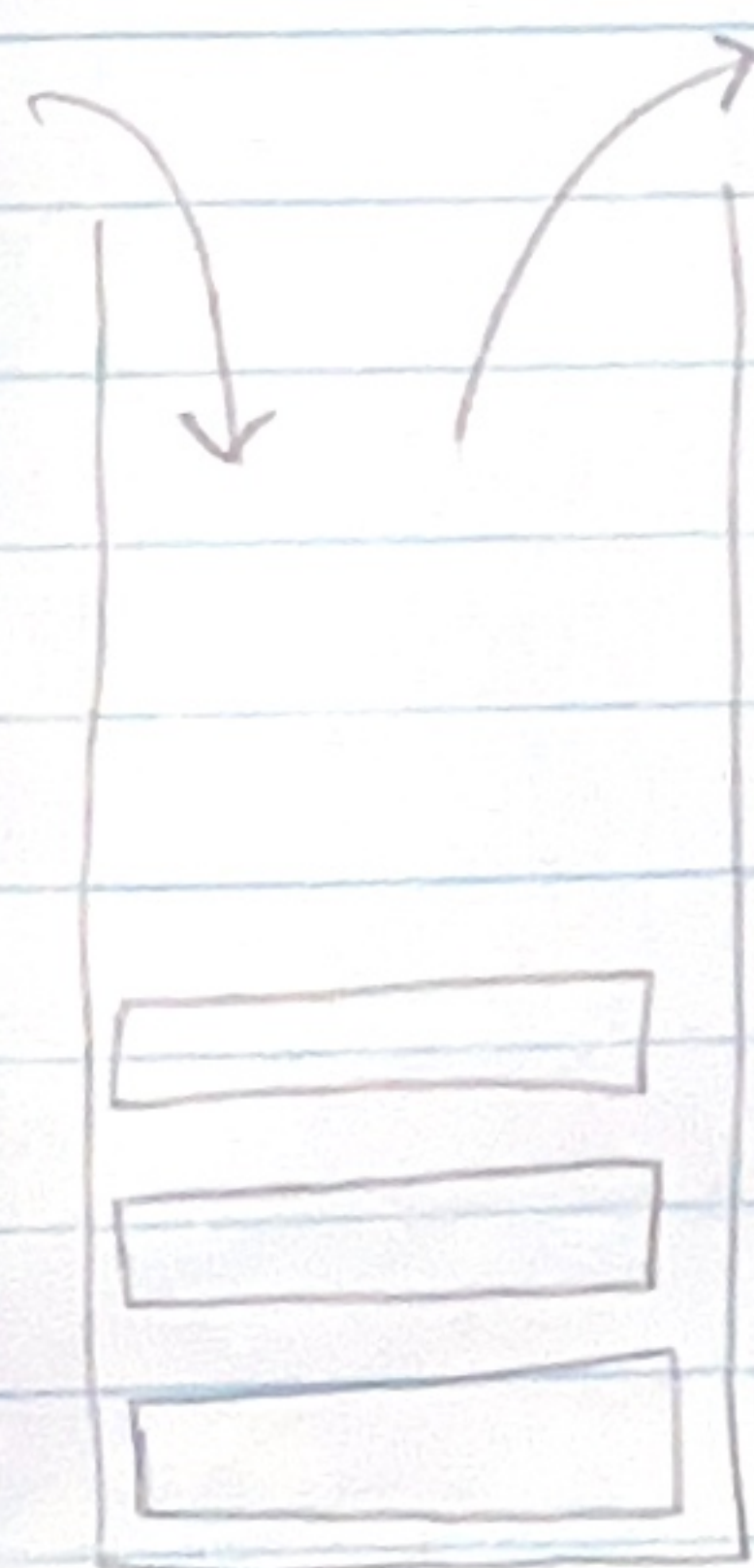
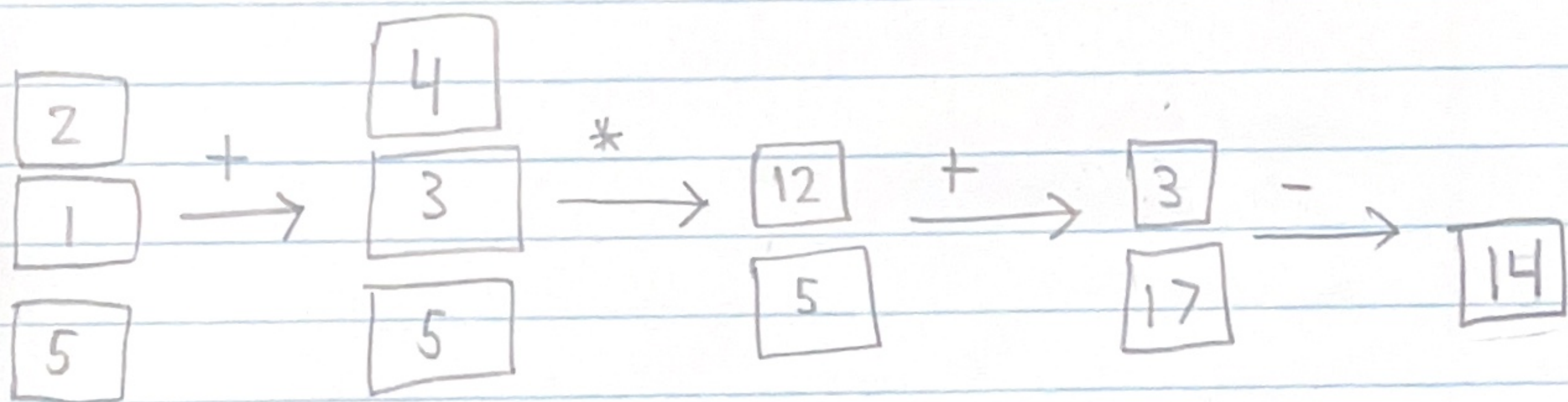
Abstract Data Types

$13 + 7 \rightarrow$ Infix

$13 \ 7 \ + \rightarrow$ Postfix or Reverse Polish Notation (RPN)

RPN

$5 \ 1 \ 2 \ + \ 4 \ * \ + \ 3 \ -$



- First in last out
- Stack

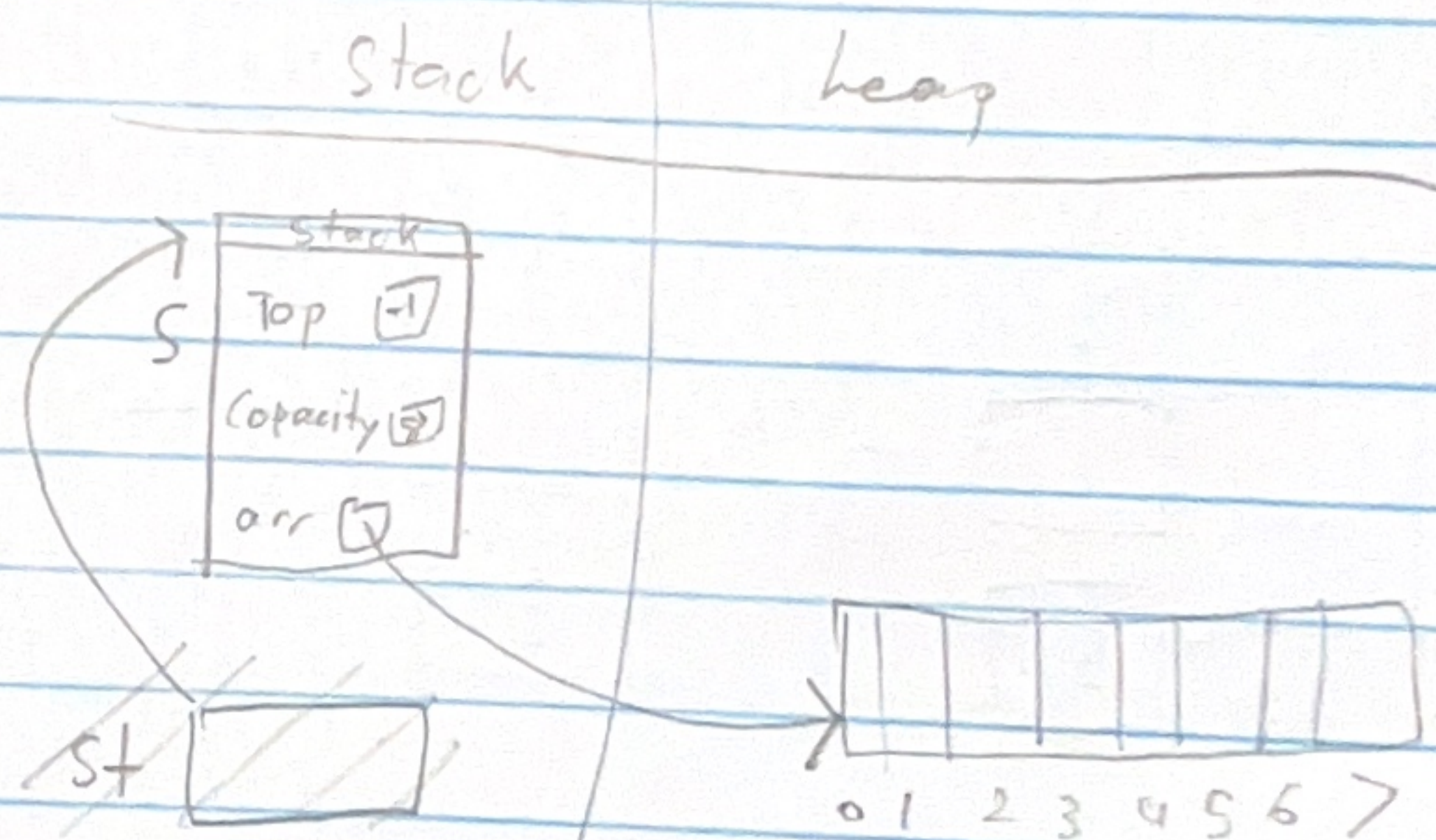
- Stack is an ADT

Stack operations

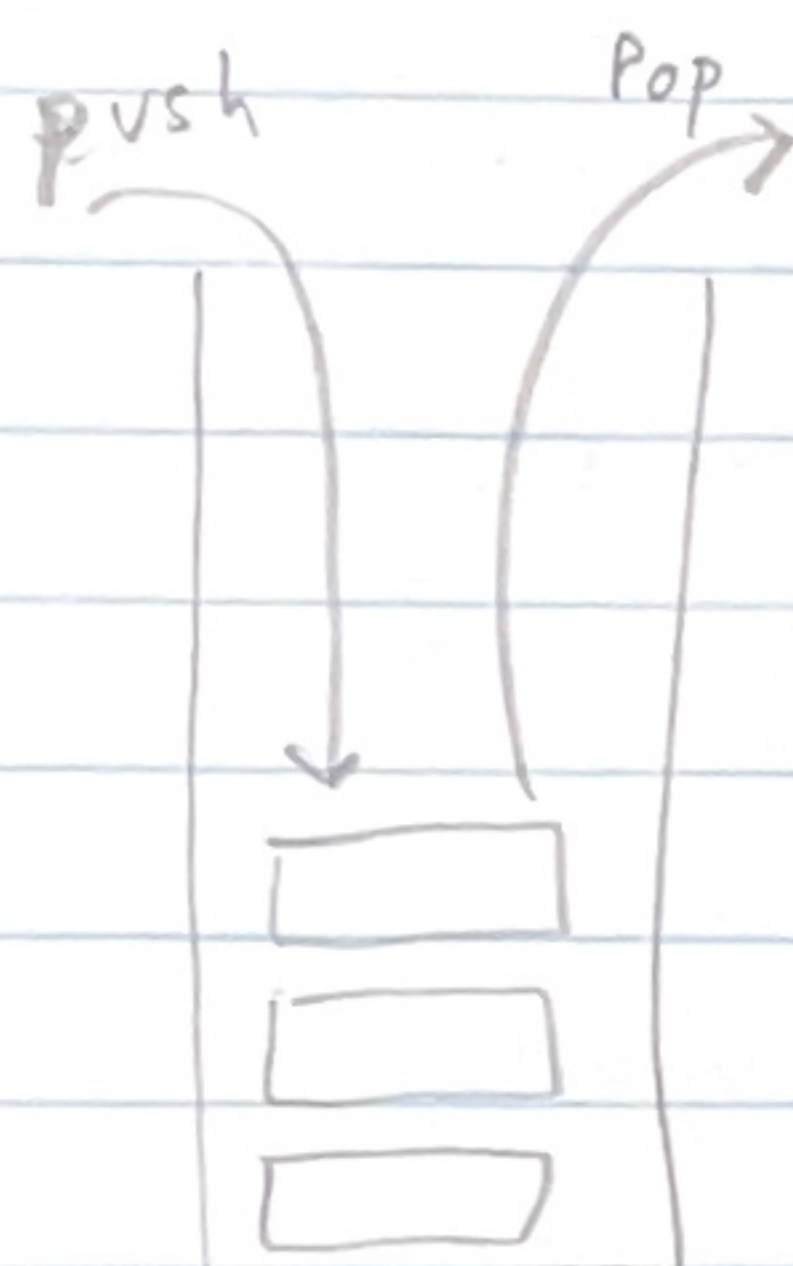
- ① Push - insert an item at the top of the stack
- ② Pop - remove and return the top item
- ③ Peek - return the top item
- ④ Is Empty - does the stack contain any items?

main ()

```
{  
    Stack s;  
    initialize(&s);  
    push(&s, 13);  
}
```

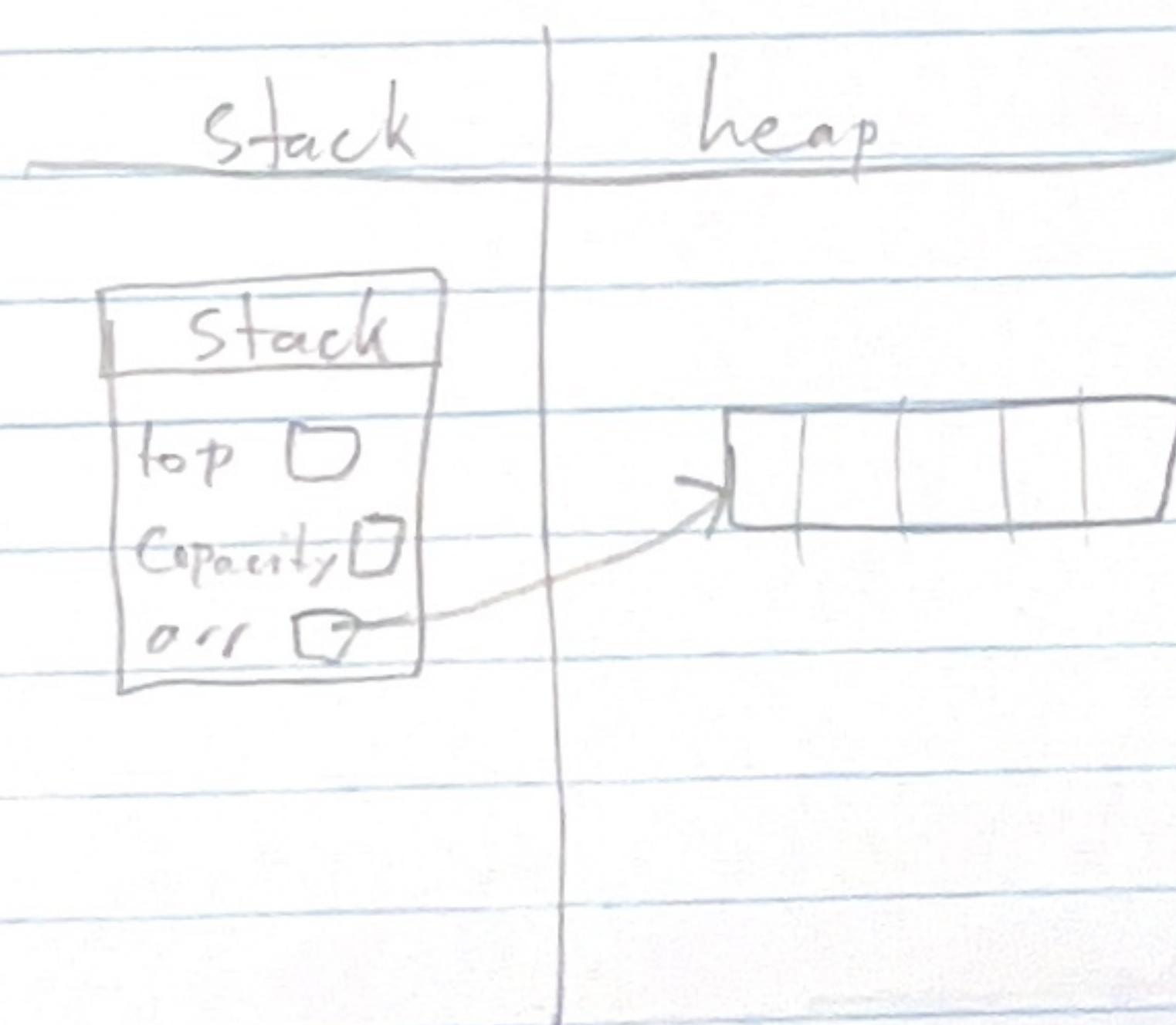


Abstract Data Types



```
typedef struct stack {
    int top;
    int capacity;
    int* arr;
} stack
```

```
stack s;
initialize_stack(&s);
push(&s, 7);
```



Complexity of push operation

(I think) $O(n)$ CHECK!!
for 2n operations

$O(1)$ per push

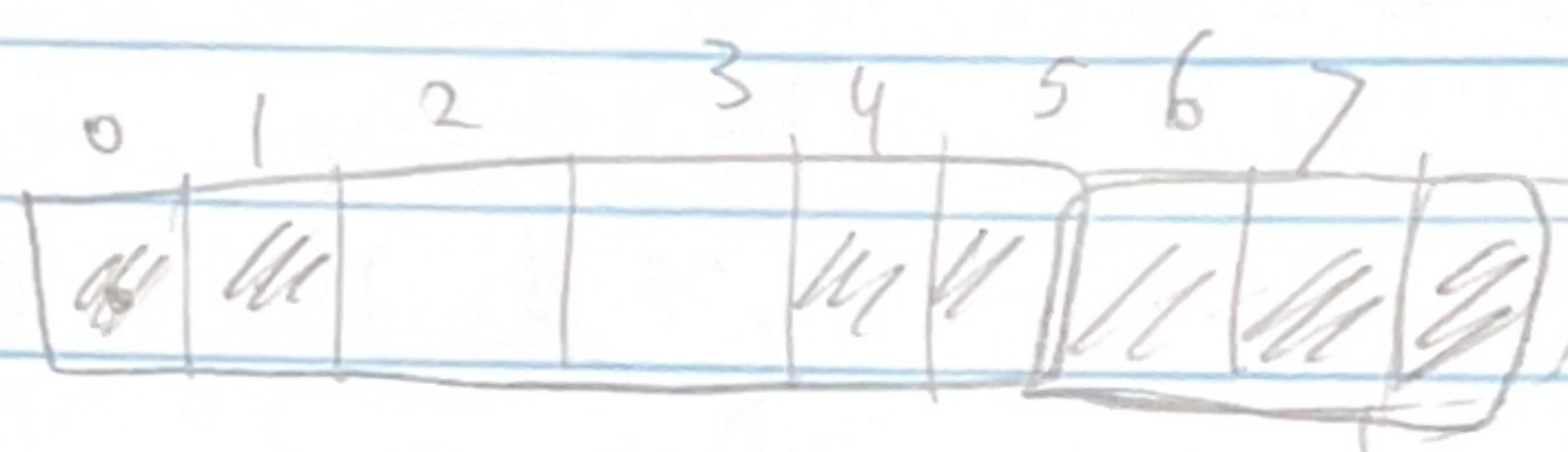
~~Bad~~ Make room by *constant factor $\rightarrow O(1)$ BETTER
Make room by +constant $\rightarrow O(n)$ WORSE

Queue

10/11/18

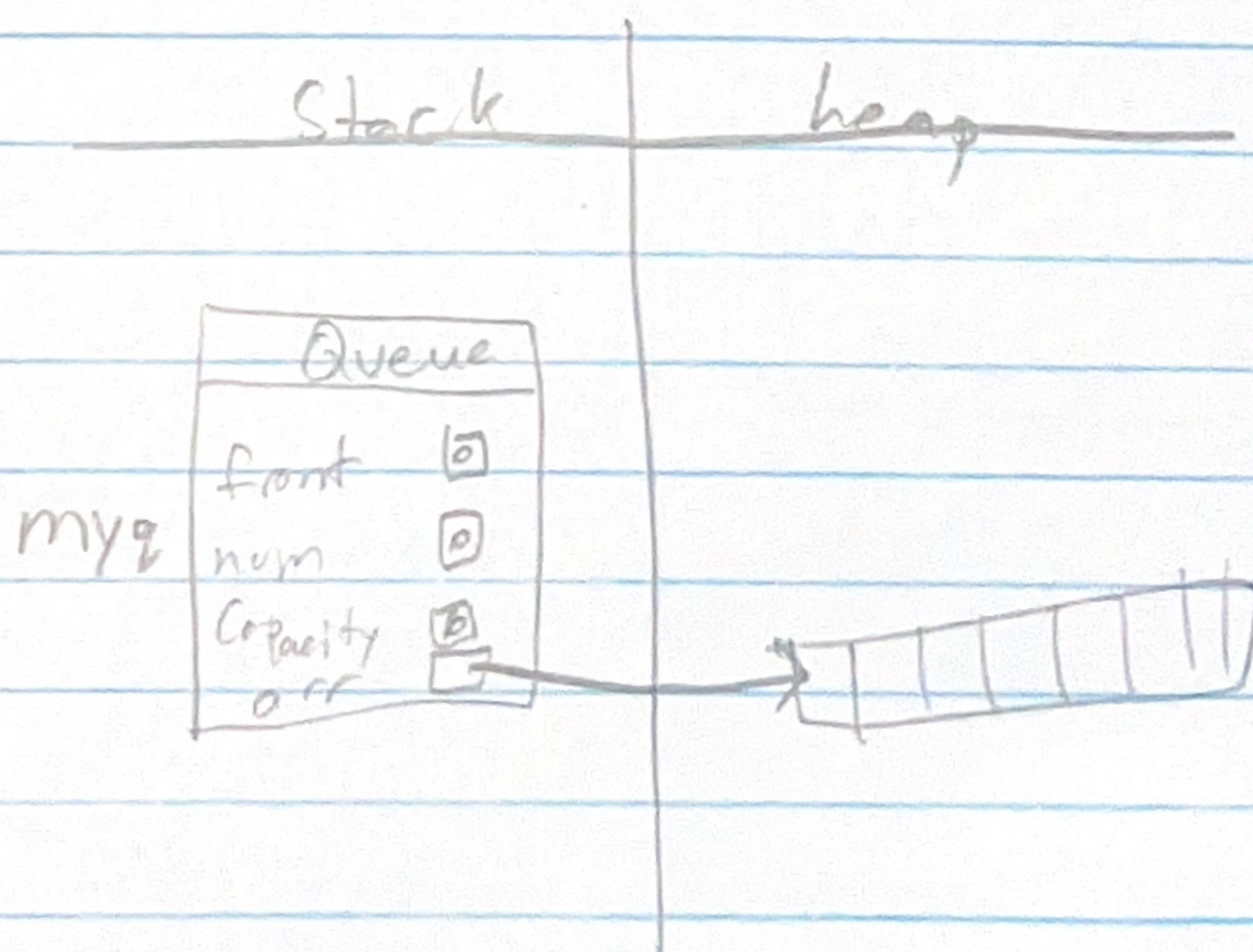
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```
typedef struct {  
    int front;  
    int num;  
    int capacity;  
    int* arr;  
} Queue;
```



$$(front + num) \% capacity = 2$$

```
Queue myq;  
init Queue (&myq);
```



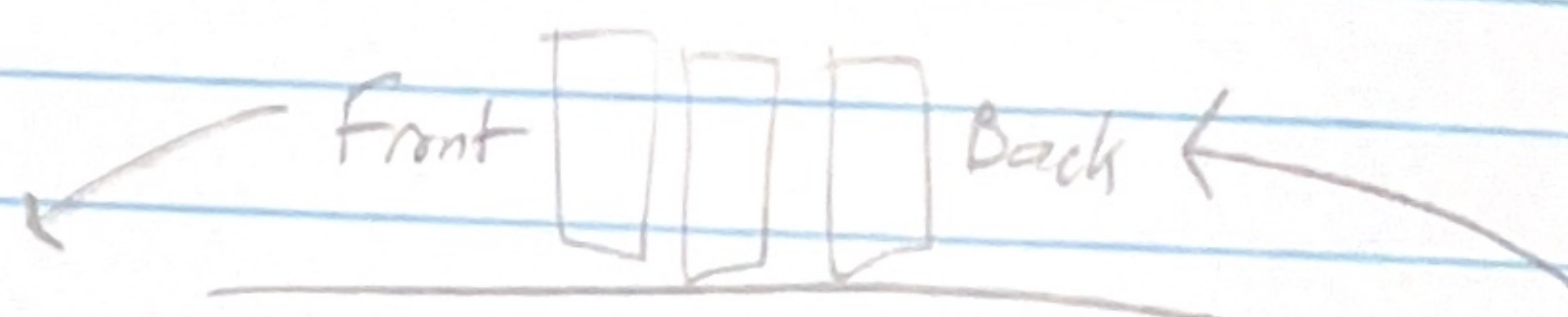
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Abstract Data Types



Stack



Queue

Commands

Peek: returns data from front of the queue

Recursion

How many
Rabbit
pairs?
Adults are
Immature

Month	1	2	3	4	5	6
Baby	1	0	1	1	2	3
Adult	0	1	1	2	3	5
Total	1	1	2	3	5	8

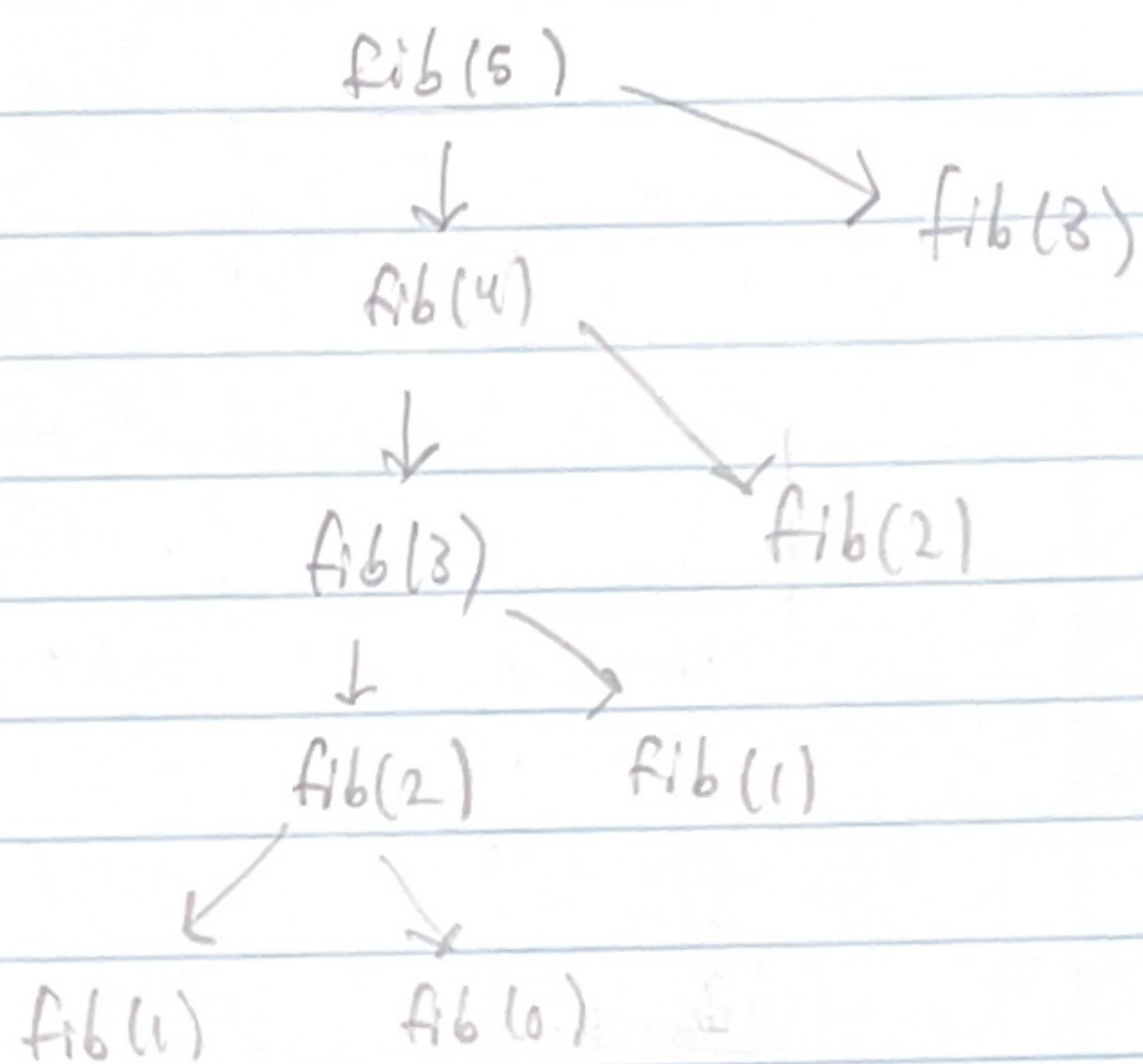
Fibonacci

- Function can call itself
- must give it parameters that are smaller each time (Fibonacci)

```

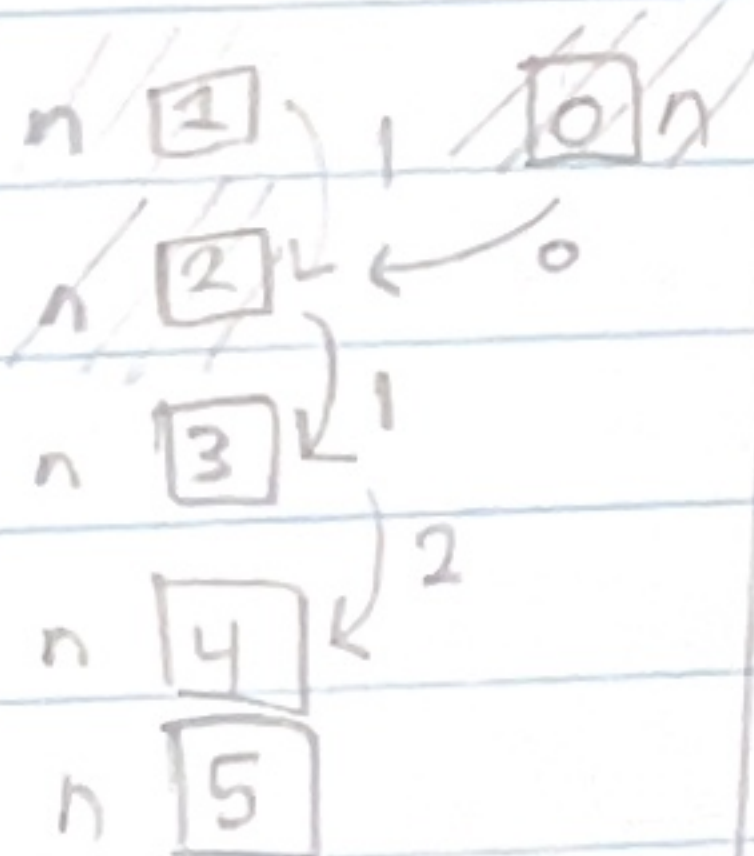
int fib(int n)
{
    if (n <= 0)
        return 0;
    else if (n == 1)
        return 1;
    else
        return fib(n-1) + fib(n-2);
}

```



Stack

heap



Recursion

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Find max in array

Iterative method

```
int findMaxIter(int arr[], int n)
{
    int maxval = arr[0];
    int i;

    for (i = 1; i < n; i++)
    {
        if (arr[i] > maxval)
            maxval = arr[i];
    }

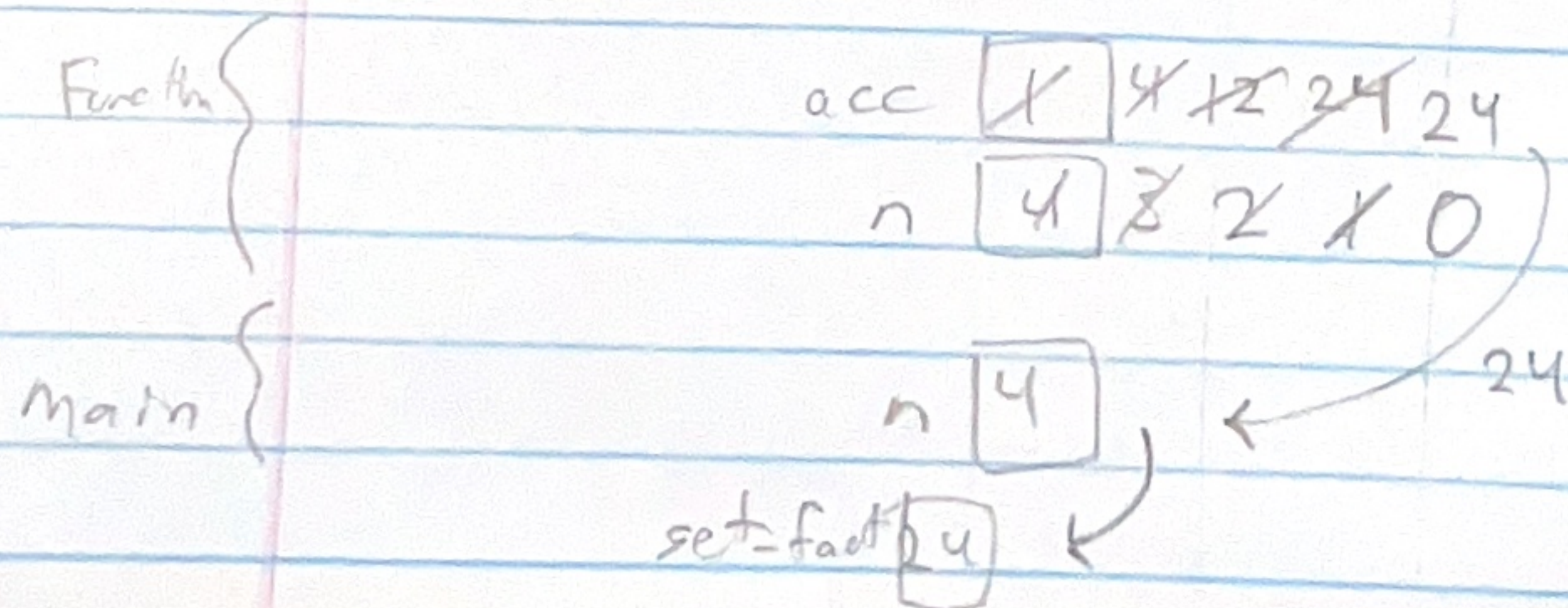
    return maxval;
}
```

Recursion functions:

- ① Factorial
- ② Find max
- ③ Summation

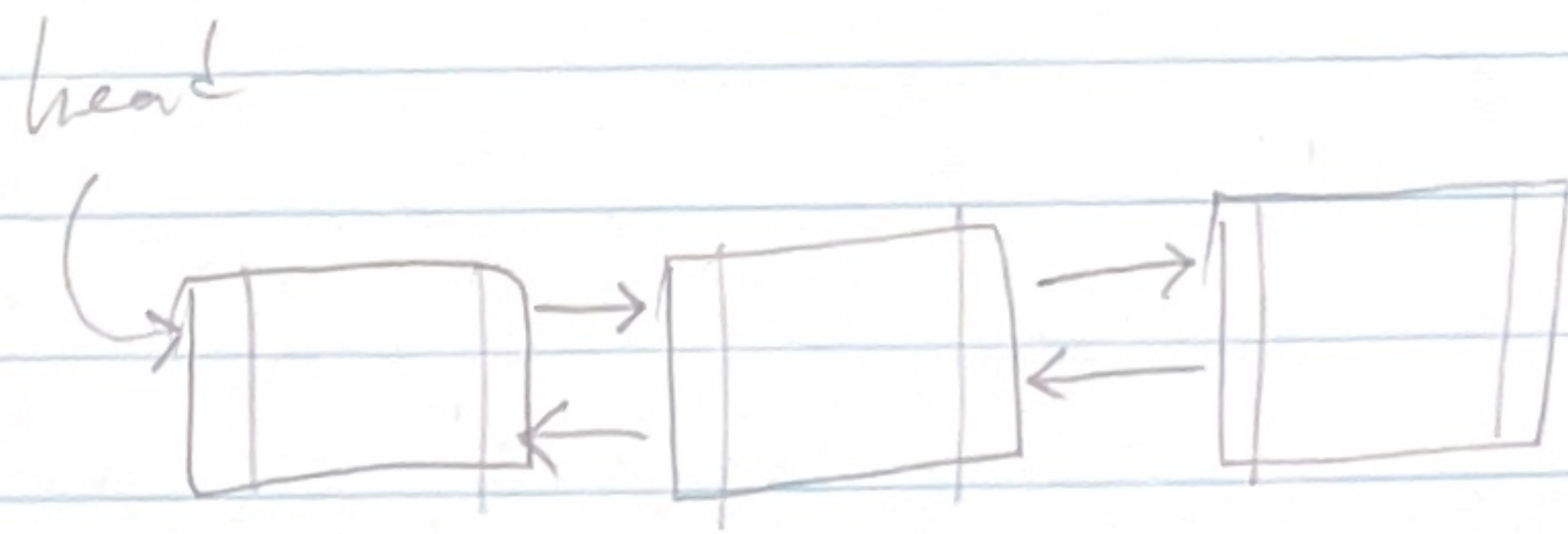
Tail Factorial Recursive

Stack

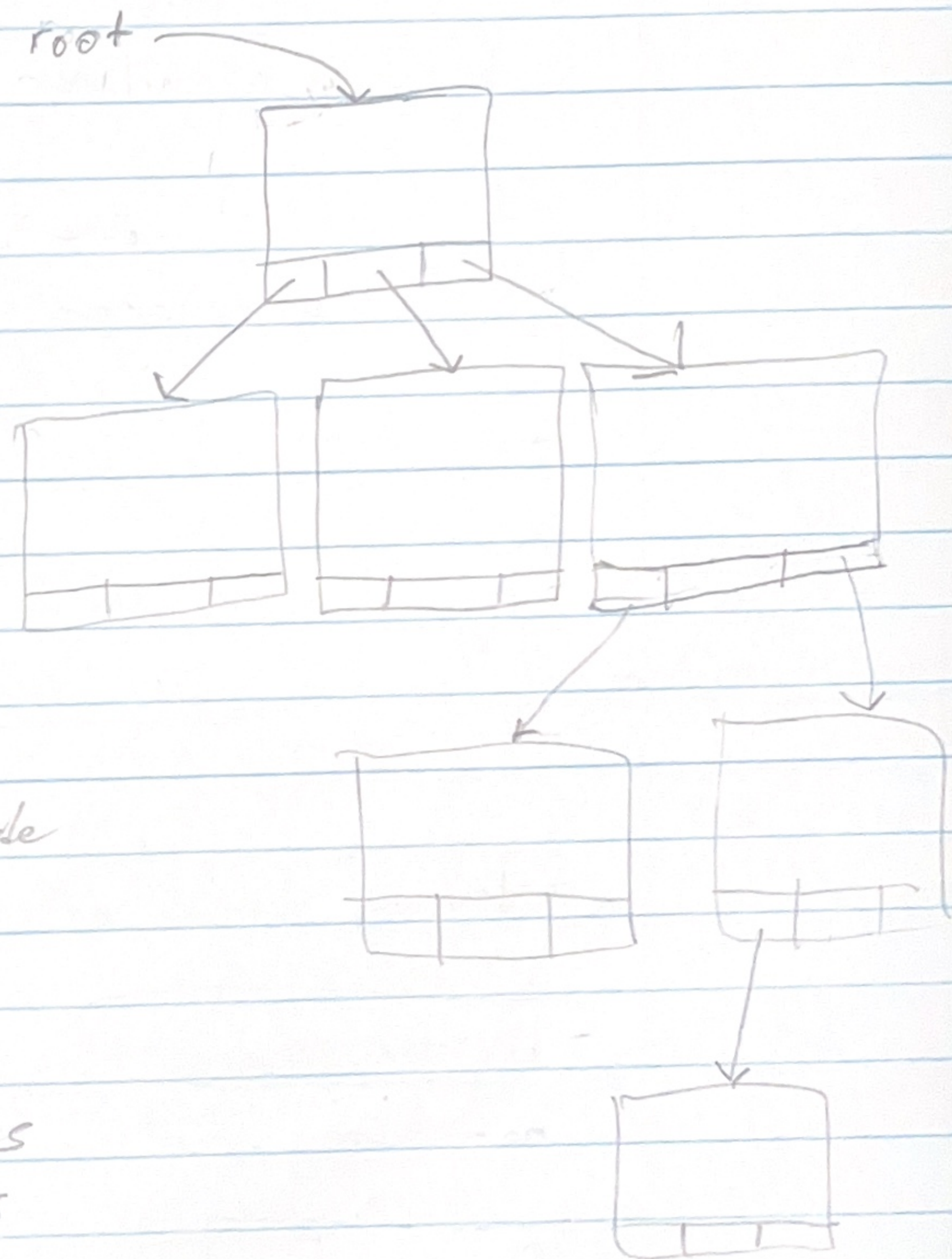


Trees

```
typedef struct LLnode {
    int data;
    LLnode* prev;
    LLnode* next;
} LLnode;
```

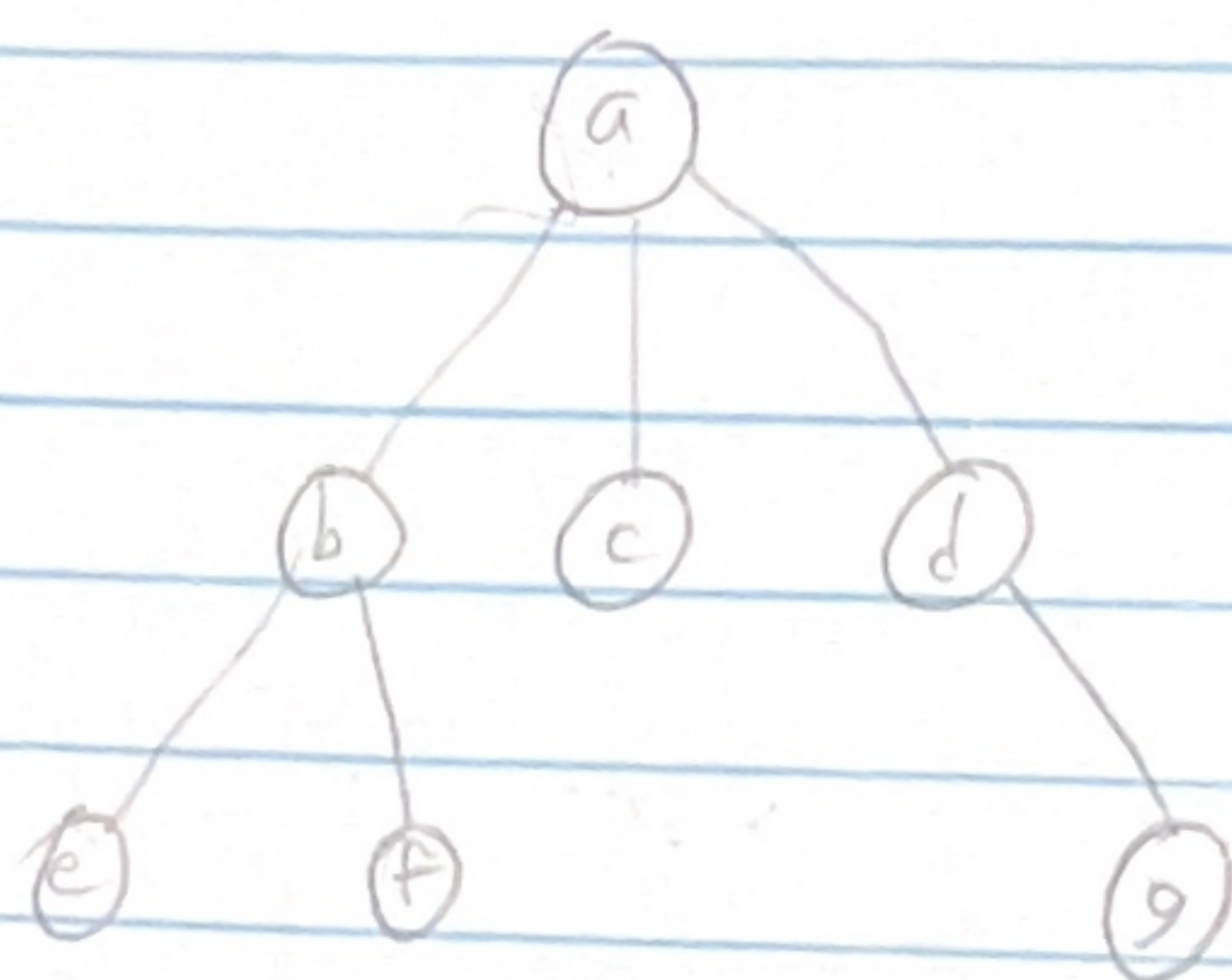


```
typedef struct treenode {
    int data;
    treenode* C1;
    treenode* C2;
    treenode* C3;
} treenode;
```



- To be a "tree", you must be able to get to every node through the root

- To be a "tree", it can have ~~more~~ number of edges as one less than number of nodes



- a is a parent of bcd
- bcd are children of a
- e and f are descendants of a
- b, c and d are siblings
- a and d are ancestors of g
- **Leaf**, node with no children
- Can have trees within trees
- **degree** number of children a node has
- **Branching factor**, the max # of children a node can have
- **Binary tree**, nodes with 2 children
- $\text{height} = 1 + \max(\text{height}(\text{left}), \text{height}(\text{right}))$;
recursive function

Binary Search Trees

Insertion

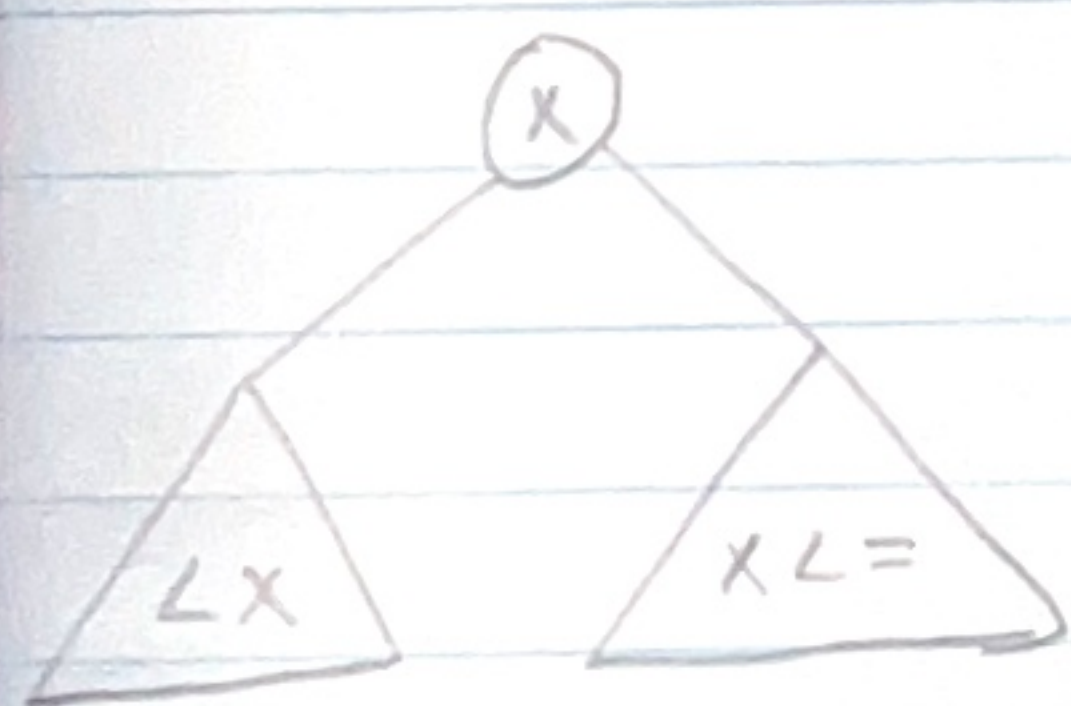
① create new node in dynamic memory

Priority Queue

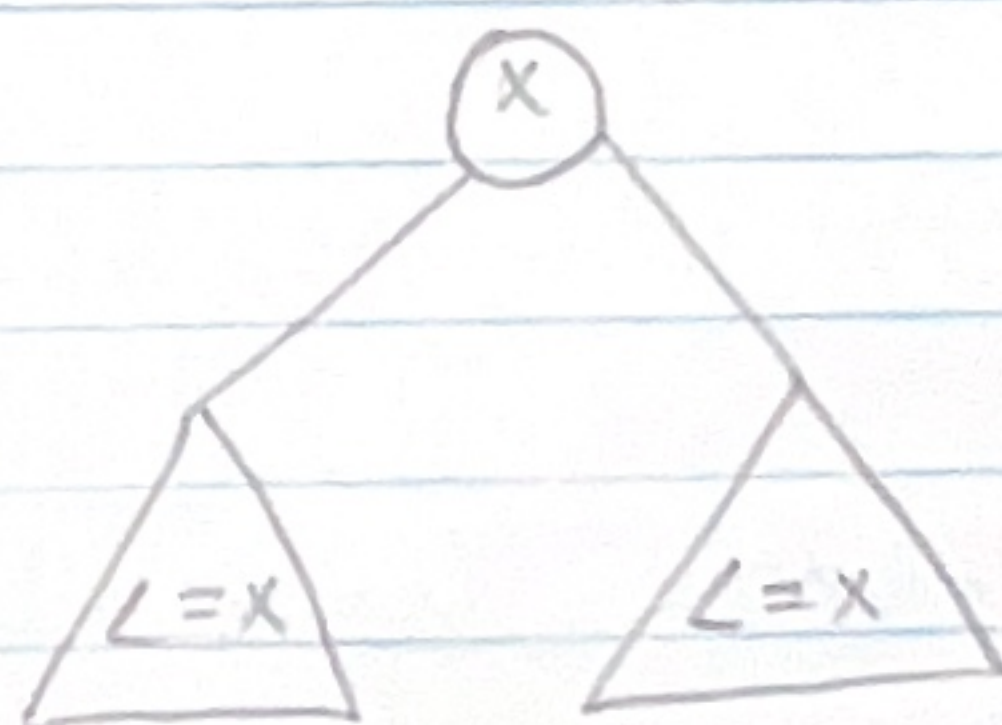
Binary heap

- Complete tree
- partially ordered

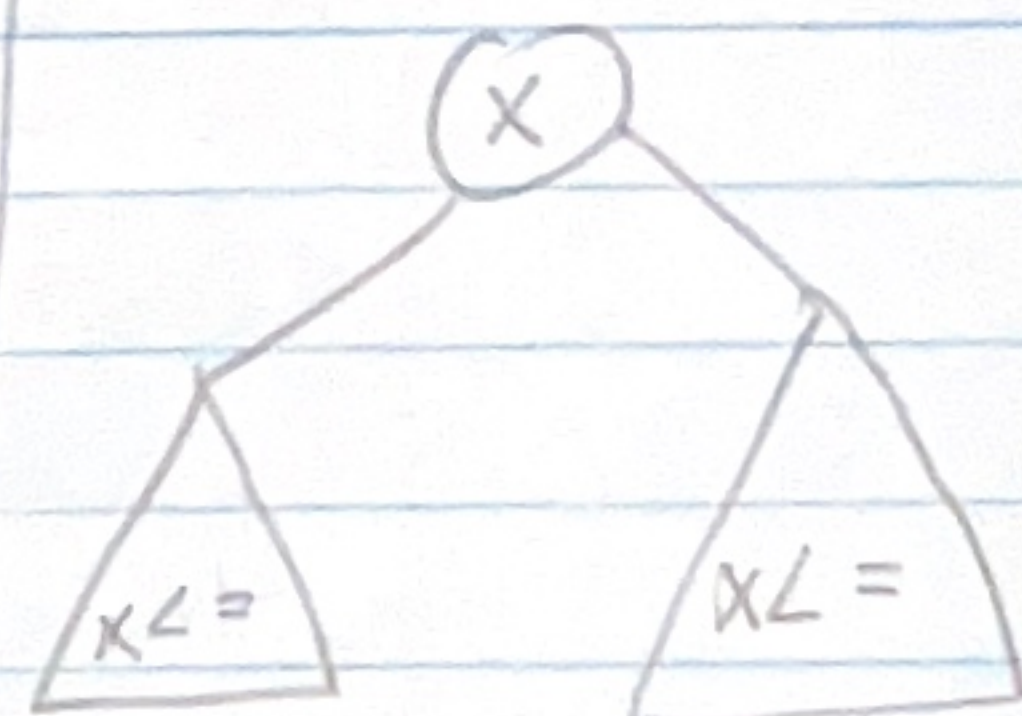
Full order



partial order (min)



partial order (max)



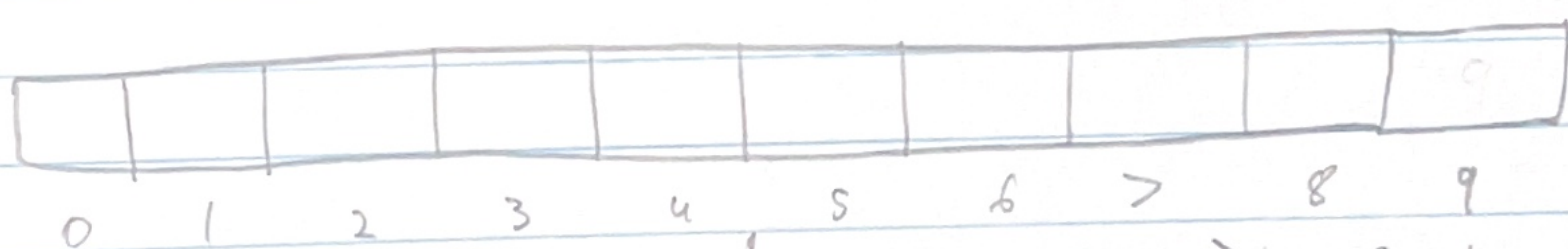
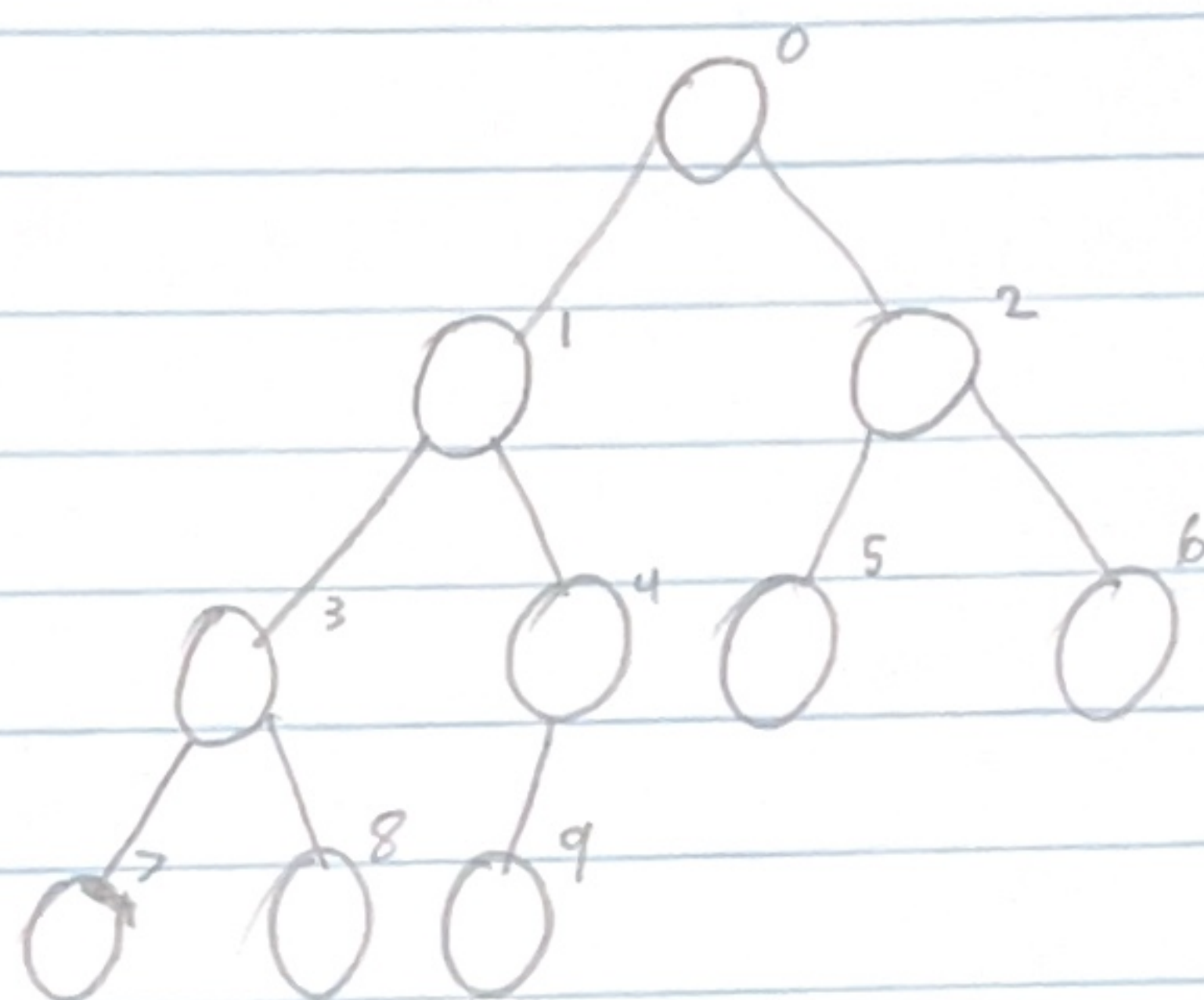
- Implemented using arrays

Heap Insertion

Time Complexity

unordered array $\rightarrow$ min heap $\rightarrow$ ordered array

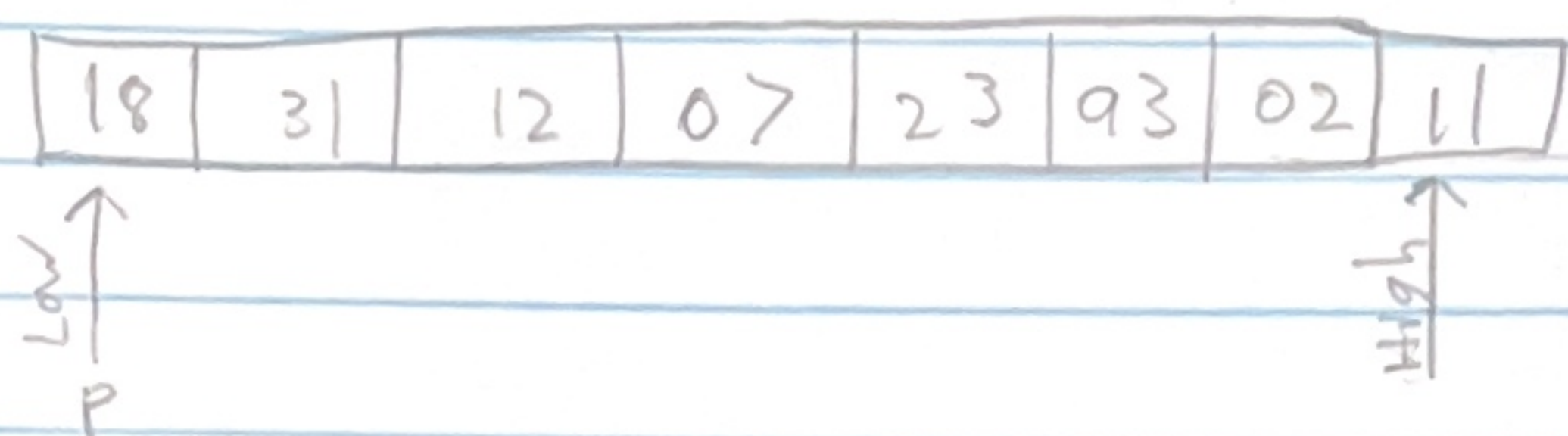
$O(n \log n)$



← Call heapify-down → leaf nodes - property satisfied

Quicksort

- Works by partitioning the array



~~pointers~~ (low high ints)

- Low
 - High
 - P
- indexes (int)

Best case

$O(n \log n)$

Worst case

n^2

Average Case

$O(n \log n)$

Loop

```
while (low != high)
```

```
{
```

```
    while (arr[high] > arr[P])
```

```
        // scan high to the left.
```

```
    // swap, set P to high index
```

```
    while (arr[low] < arr[P])
```

```
        // scan low to the right
```

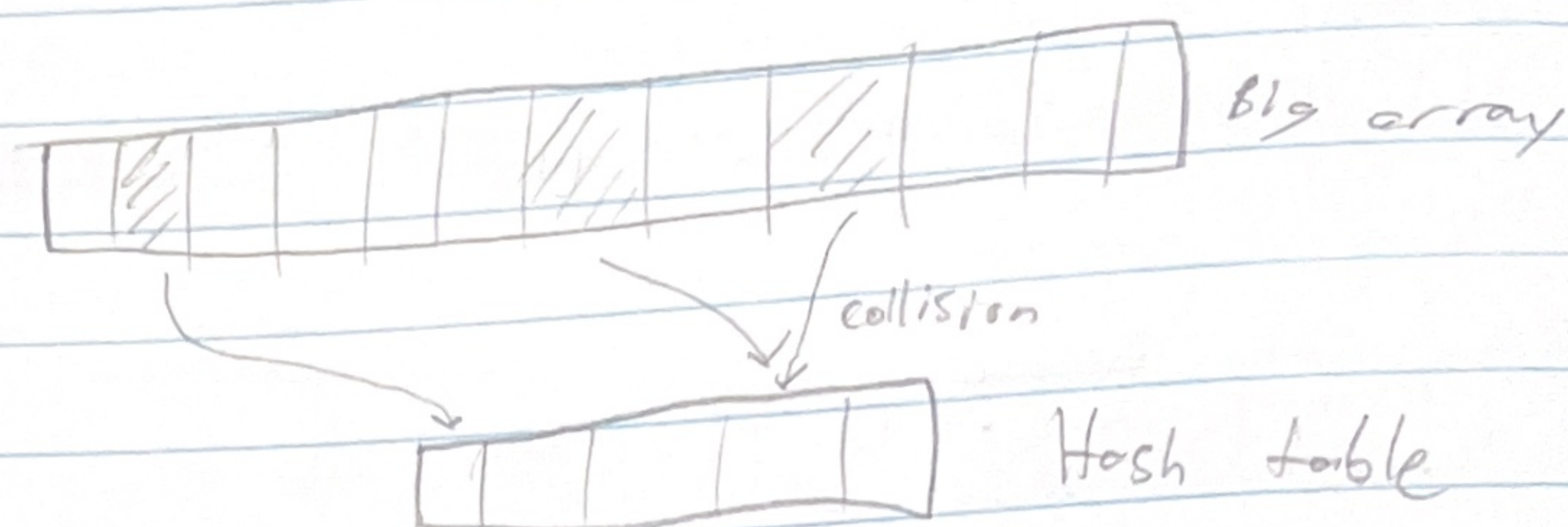
```
    // swap, set P to low index
```

```
}
```

Hash Tables

11/26/18

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Collision

$f(x_1) = f(x_2) \rightarrow$ collision will occur

Hash function Properties

- ① Fast $\rightarrow$ want $O(1)$ complexity
- ② Deterministic $\rightarrow$ not random
- ③ Uniformity

- Convert "Strings" $\rightarrow$ int value

hash function $\rightarrow h(x) = x \% \text{table size}$

Deal with collisions how?

- ① Open addressing
- ② Separate chaining

Open addressing

- You go to put your (struct, value) in the hash table but there is already something there. So you
sol'n probe array (linear) find another free space